STOCHASTIC CONTINUOUS NORMALIZING FLOWS TRAINING SDES AS ODES

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NEURAL ODES	CONTINUOUS NORMALIZING FLOW	NEURAL SDES
Ordinary differential equations (ODEs) formed from single-(or multi-)layer neural networks are called <i>neural ODEs</i> :		An Itô stochastic differential equation (SDE) is of the form
$\frac{\mathrm{d}}{\mathrm{d}t}Z(t) = f(Z(t), t, \theta). \tag{1}$	tinuous normalizing flow [1, 2]. It can be trained by <i>maximum likelihood</i> <i>estimation</i> or <i>variational inference</i> using	$dZ_t = \mu(Z_t, t, \theta) dt + \sigma(Z_t, t, \theta) dB_t$, (3) where B_t is Brownian motion , μ is the drift,
They can be trained with the <i>adjoint method</i> [1].	Theorem (Chen et al., 2018). If $Z(t)$ satisfies (1), the probability density p_t of $Z(t)$ satisfies	and - the diffusion coefficient

STRATONOVICH CORRECTION

STEP 1

Because the chain rule does not hold in Itô calculus, *naive approximations do not work*.

Solution: Use a different calculus

The Itô SDE (3) can be *converted to a Stratonovich SDE*:

 $dZ_t = \tilde{\mu}(Z_t, t, \theta)dt + \sigma(Z_t, t, \theta) \circ dB_t,$ (4)

using a Stratonovich drift correction.

Stratonovich SDEs satisfy the chain rule, and *behave like ODEs* (reversible, approximable).

$\frac{\mathrm{d}}{\mathrm{d}t} \log p_t(Z(t)) = -\nabla_z \cdot f(Z(t), t, \theta)$ (2)

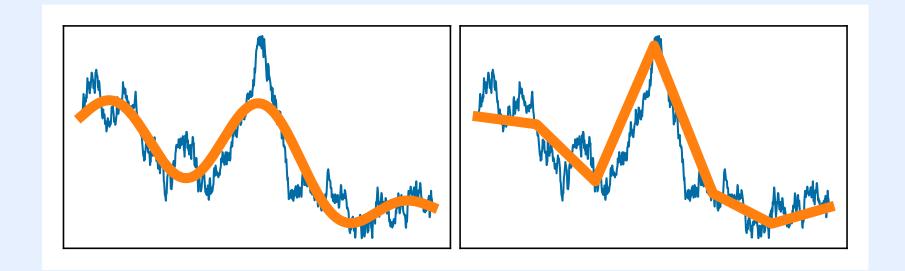
WONG-ZAKAI APPROXIMATION

STEP 2

Let $B(t) \approx B_t$ be a pathwise **approxima**tion of Brownian motion.

Approximations include:

- *Piecewise linear:* Linear interpolation of Gaussian random walk—recovers Euler scheme.
- *Karhunen-Loève expansion:* A smooth Fourier series for Brownian motion.



injectea noise.

Problem: Training SDEs is often complex.

Objective: Develop a general procedure for training SDEs using ODE training procedures.

Three Steps:

- 1. Perform a Stratonovich drift correction
- 2. Approximate the Brownian motion
- 3. Train the resulting random ODE

TRAINING A RANDOM ODE

STEP 3

The approximation (5) is an **ODE** with latent variable B(t). It can be trained using

REGULARIZATION

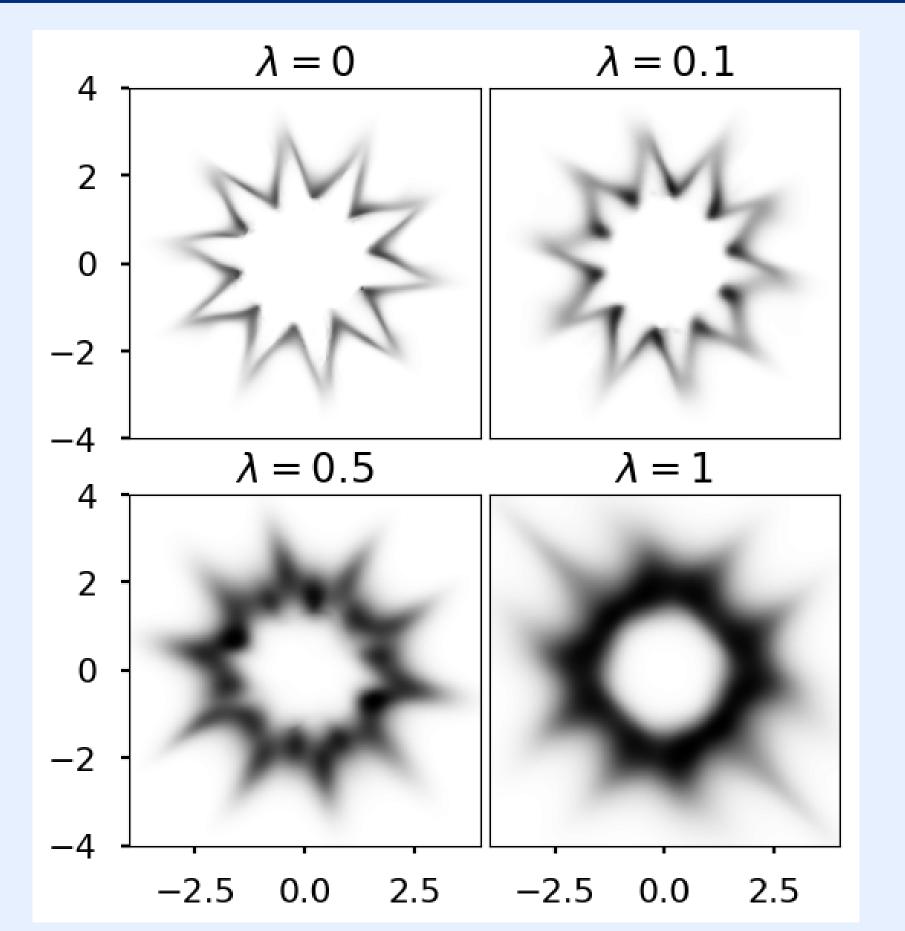


Figure 2: Fitting a star-shaped density with *stochastic continuous normalizing flows* with drift parameterized by a 3-layer NN, and diffusion coefficient λI . Increasing the diffusion adds a *regularization* effect to the fit. Figure 1: Approximations (orange) of Brownian motion (blue): (left) Karhunen-Loève; (right) linear spline/Euler

A *Wong–Zakai approximation* of (4) is the random ODE

$$\frac{\mathrm{d}}{\mathrm{d}t}Z(t) = \tilde{\mu}(Z(t), t, \theta) + \sigma(Z(t), t, \theta) \frac{\mathrm{d}B(t)}{\mathrm{d}t}$$
(5)

SAMPLERS

Langevin diffusions are commonly used as *sampling algorithms*. Can we learn them?

5	fixed σ	variable σ
5		

any ODE training procedure.

Metatheorem. The following procedures are consistent as $B(t) \rightarrow B_t$.

- Stochastic adjoint method: Adjoint method applied to (5)—equivalent to [3].
- **Density estimation:** Monte Carlo estimation for density using (2).
- Stochastic continuous normalizing flow (SCNF): Perform semi-implicit variational inference using (2).

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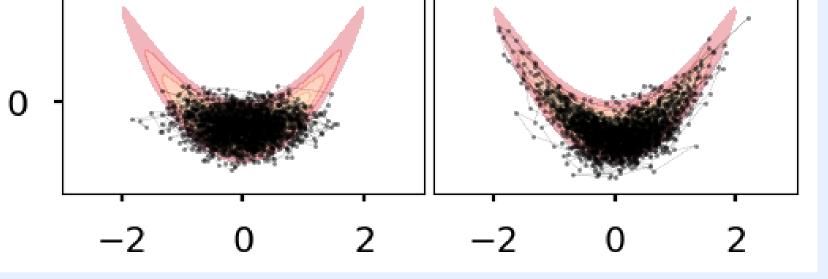


Figure 3: Simulating SDEs trained to a banana target distribution with drift parameterized by a 3-layer NN. (left) Diffusion coefficient is fixed $\sigma \equiv I$; (right) Diffusion coefficient parameterized by 3-layer NN.

[2] Will Grathwohl, Ricky TQ Chen, Jesse Bettencourt, Ilya Sutskever, and David Duvenaud. FFJORD: Free-form continuous dynamics for scalable reversible generative models. *arXiv* preprint arXiv:1810.01367, 2018.

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